

# Scalable Bayesian seismic wavelet estimation

Guillermina Senn<sup>1</sup>

jointly with Matt Walker<sup>2</sup>, Håkon Tjelmeland<sup>1</sup>, and Andrew Holbrook<sup>3</sup>

<sup>1</sup>Norwegian University of Science and Technology (NTNU)

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Lofotseminaret i anvendt geofysikk  
August 21, 2025

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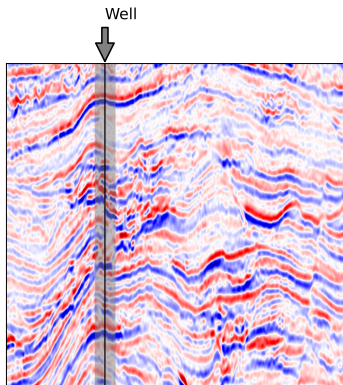
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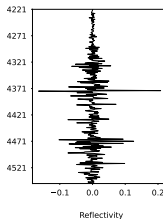
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# Summary

## 1. Data



(a) Seismic data



(b) Well-log

## 2. Model

1D convolutional model

$$d_j = c_j \star w + e_j \quad \text{for column } j.$$

+ Bayesian probabilistic model, on a cyclic lattice .

## 3. Scalable wavelet estimation

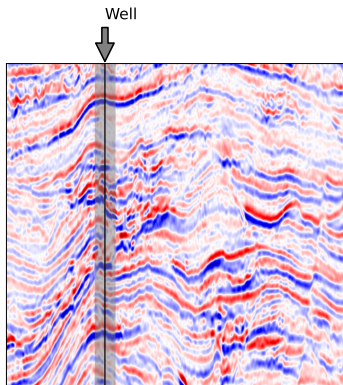
Sample posterior distribution

$$p(c, w, \sigma_c^2, \sigma_w^2, \sigma_d^2 \mid d)$$

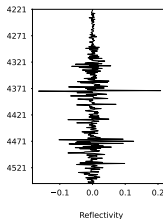
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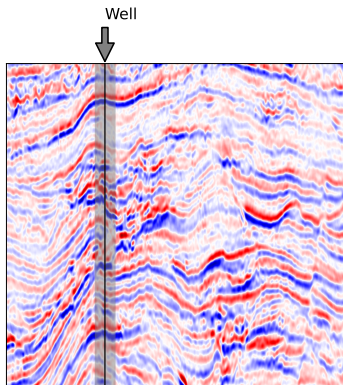
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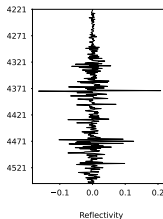
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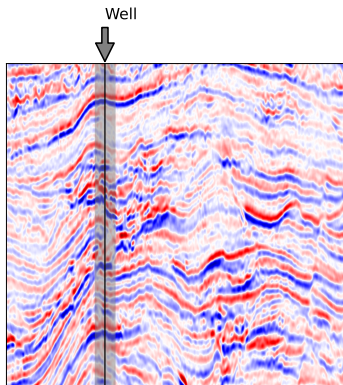
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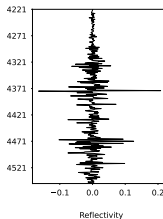
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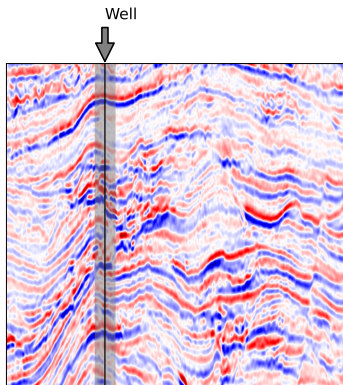
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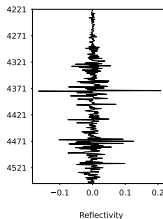
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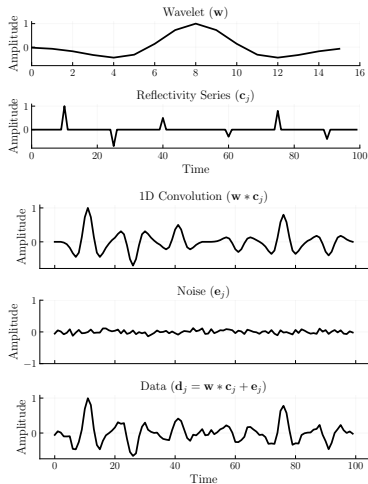
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# The 1D convolutional model



Single trace  $j$ :

- $d_j, c_j, e_j \in \mathcal{R}^n$
- $w = \{w_0, \dots, w_{k-1}\} \in \mathcal{R}^k$
- 1D convolutional model is

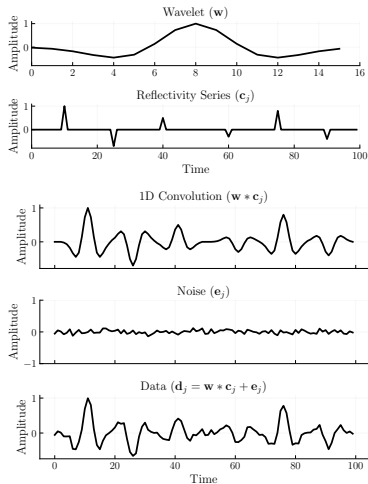
$$d_j = w * c_j + e_j \quad (1)$$

Image with  $m$  traces:

- $d, c, e \in \mathcal{R}^{nm}$ .
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$$d = Wc + e.$$

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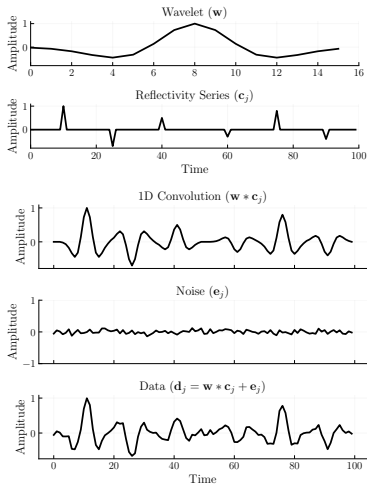
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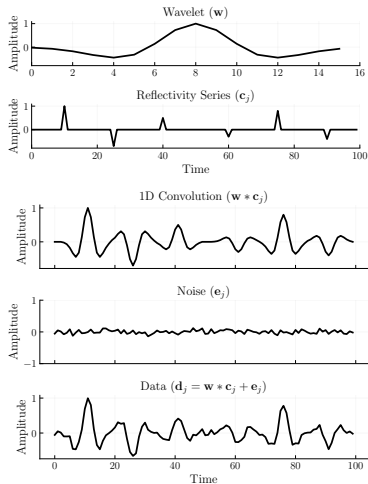
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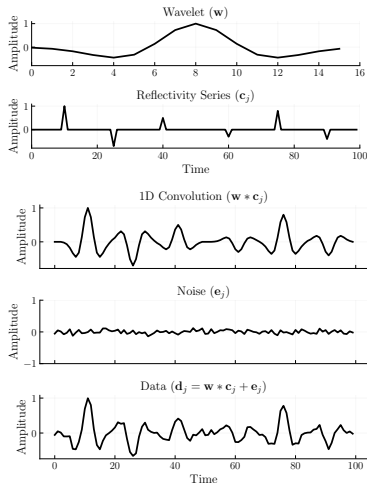
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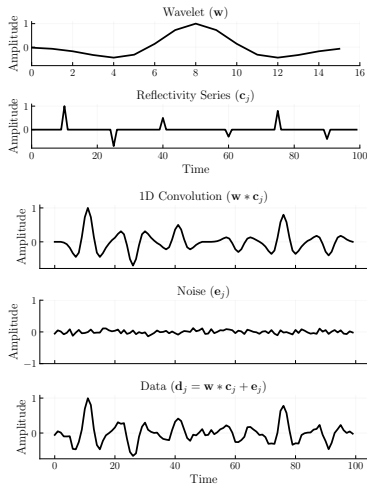
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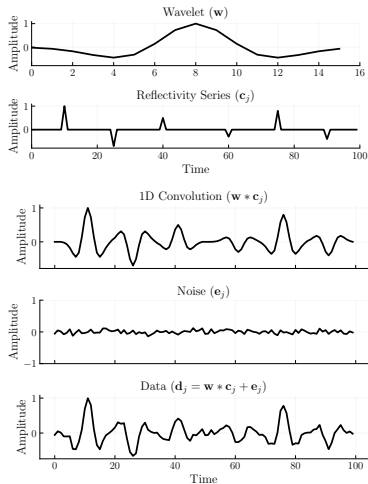
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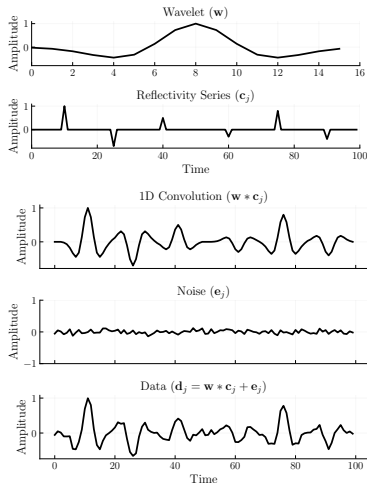
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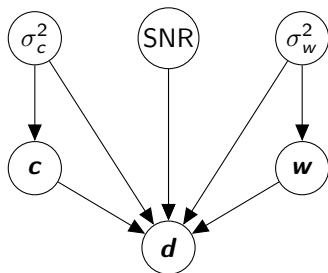
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# The Bayesian model

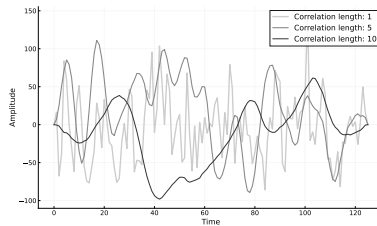


DAG of the model.

- Gaussian wavelet with inverse-gamma variance:

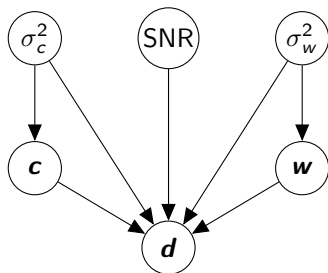
$$\mathbf{w} \sim N_k(\boldsymbol{\mu}_w, \sigma_w^2 \mathbf{R}_w), \quad \sigma_w^2 \sim IG(\alpha_w, \beta_w)$$

- Endpoints are constrained to zero.



Samples from the wavelet prior.

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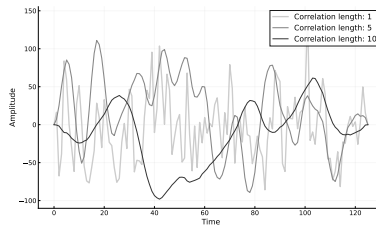


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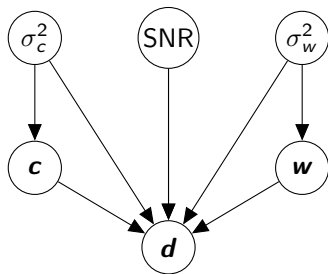
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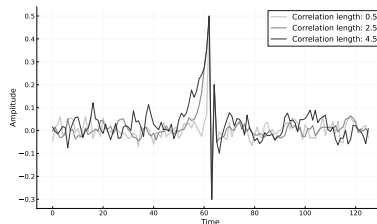


DAG of the model.

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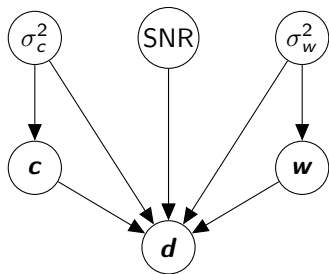
$$\mathbf{c} \sim N_{nm}(\boldsymbol{\mu}_c, \sigma_c^2 \mathbf{R}_c), \quad \sigma_c^2 \sim IG(\alpha_c, \beta_c).$$

- Hard-constrained with well values.



Samples from the reflectivity prior (one trace).

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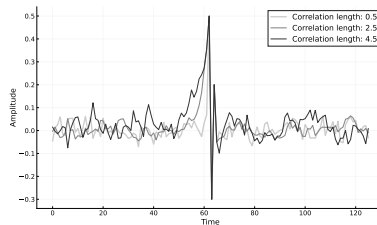


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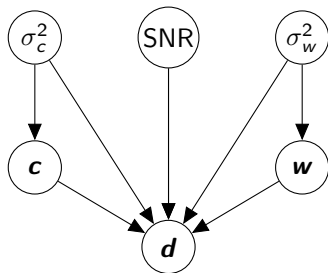
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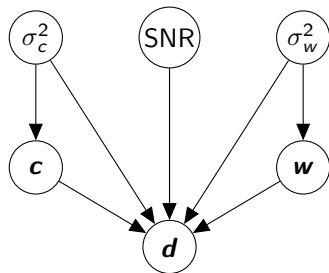
- Model the signal-to-noise ratio as stochastic

$$SNR = \frac{\text{Var}(\mathbf{w} \star \mathbf{c})}{\sigma_d^2} \iff \sigma_d^2 = \frac{\text{Var}(\mathbf{w} \star \mathbf{c})}{SNR}; \quad \text{Var}(\mathbf{w} \star \mathbf{c}) = \psi \sigma_c^2 \sigma_w^2$$

- Gaussian observational noise with Gamma SNR:

$$\mathbf{d} | \mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, SNR \sim N_{nm}(\mathbf{W}\mathbf{c}, \sigma_d^2 \mathbf{R}_d), \quad SNR \sim \text{Gamma}(\alpha_{SNR}, \beta_{SNR})$$

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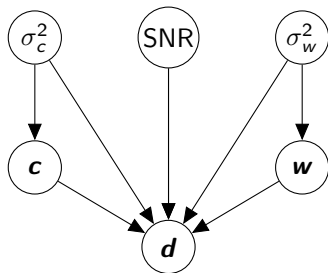
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- Bayes' rule

$$p(\boldsymbol{\theta}|\mathbf{d}) = \frac{p(\boldsymbol{\theta}, \mathbf{d})}{p(\mathbf{d})} \propto p(\mathbf{d}, \boldsymbol{\theta})$$

gives

$$p(\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta|\mathbf{d}) \propto p(\mathbf{d}|\mathbf{c}, \mathbf{w}, \sigma_c^2, \sigma_w^2, \zeta)p(\mathbf{c}|\sigma_c^2)p(\mathbf{w}|\sigma_w^2)p(\sigma_c^2)p(\sigma_w^2)p(\zeta).$$

- The model is proposed on an extended cyclic lattice for scalability <sup>1</sup>
- We sample this intractable density with MCMC.

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# MCMC on the cyclic lattice

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**Algorithm** A general MCMC scheme

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Initialize ...

**for**  $t = 1, 2, \dots, T$  **do**

**Update wavelet**

        Update reflectivity

        Update reflectivity variance

        Update wavelet variance

        Update SNR

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- A: **Update wavelet** from its full conditional: Gibbs sampler
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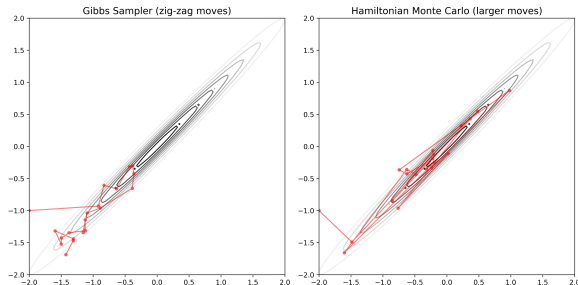
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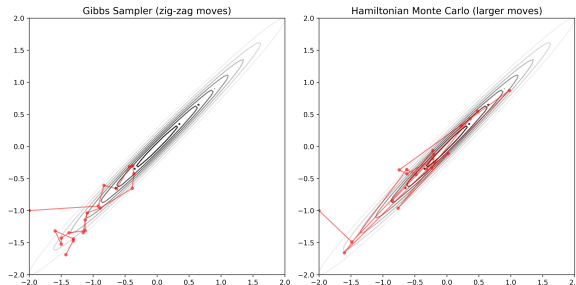


Posterior exploration of a correlated Gaussian.

- HMC explores regions with high mass (density  $\times$  volume).
- HMC moves between points following a trajectory of length  $\varepsilon L$ , defined by a Hamiltonian system.
- Must tune step size  $\varepsilon$  and number of steps  $L$  in the numerical integrator.

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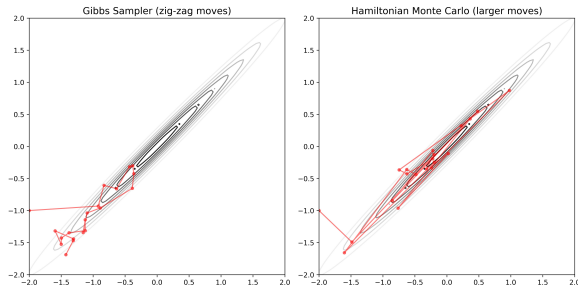


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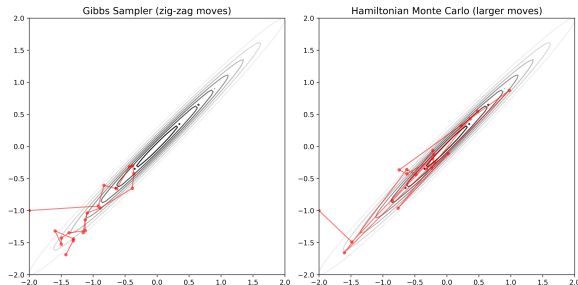


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# Wavelet update with Hamiltonian Monte Carlo

- We want to avoid random walk behaviour in high dimensions.

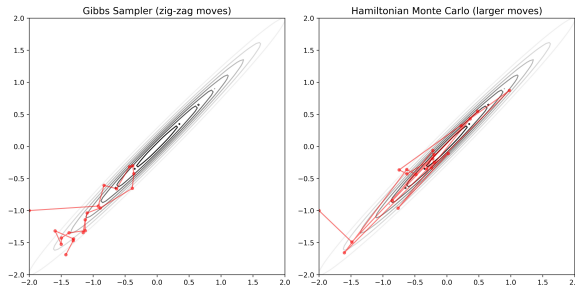


Posterior exploration of a correlated Gaussian.

- HMC explores regions with high mass (density  $\times$  volume).
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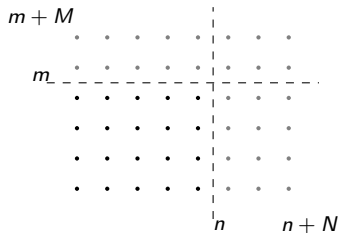
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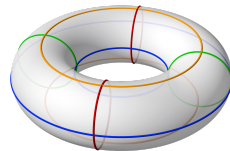
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# Scalability



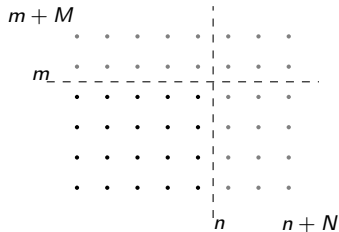
(a) The lattice is extended with  $M$  rows and  $N$  columns



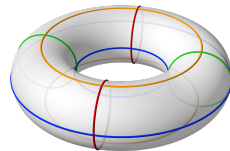
(b) The cyclic lattice.

- The covariance and convolutional matrices become circulant.
- We only need to store their first row.
- Circulant matrix algebra is done with the FFT on the first row.
- Fast evaluation of full conditional parameters in Gibbs and gradients in HMC.

# Scalability



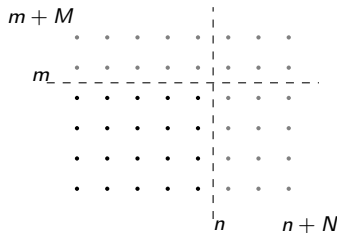
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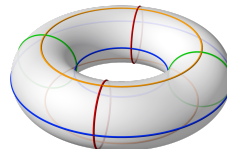
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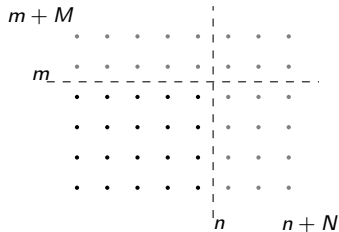
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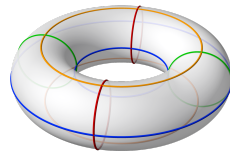
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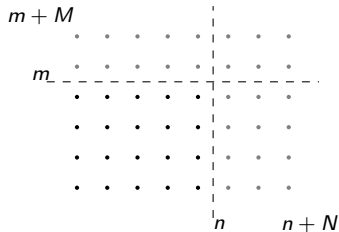
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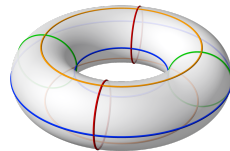
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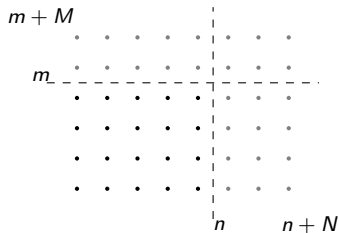
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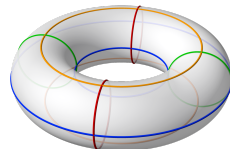
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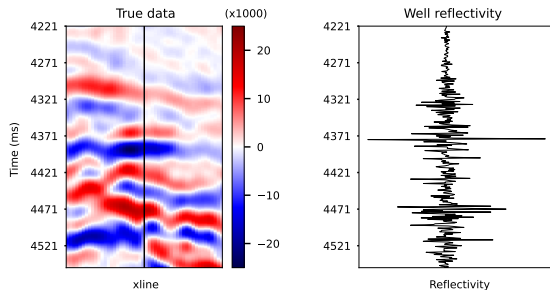
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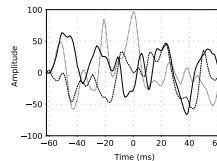
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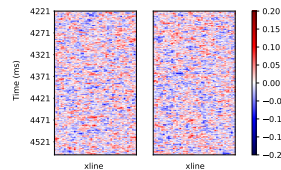
# Real application: Gas reservoir in offshore Egypt



330x50ms AVO window and well reflectivity.

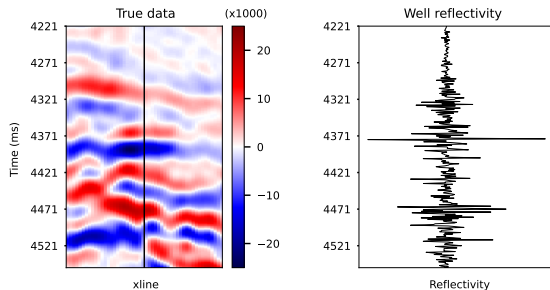


(a) Wavelet prior samples.

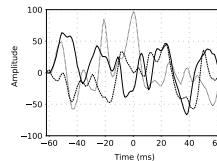


(b) Reflectivity prior samples.

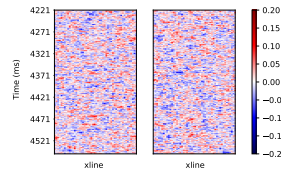
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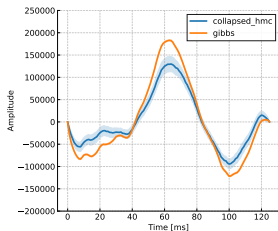
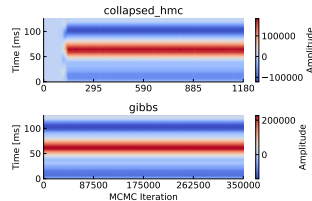
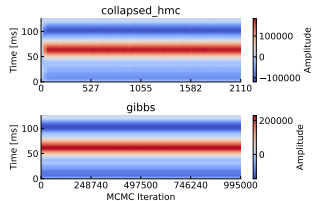
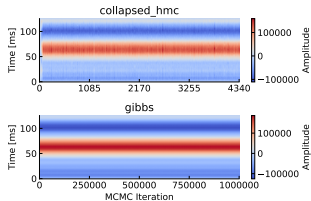


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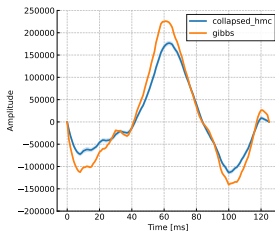


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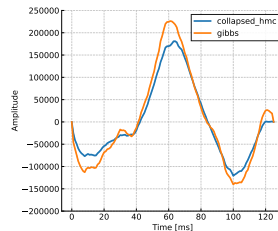
# Preliminary wavelet estimation results



(a) Well trace.

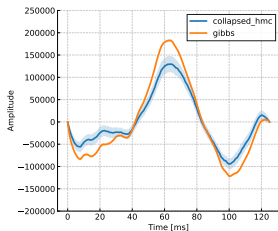
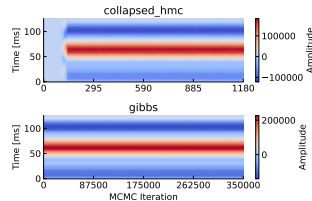
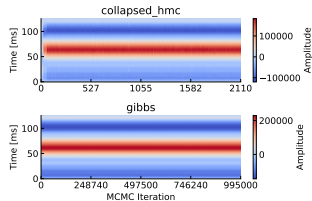
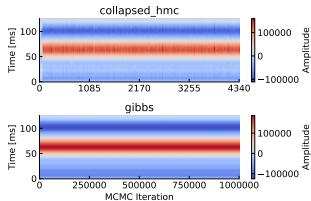


(a) 330x10ms.

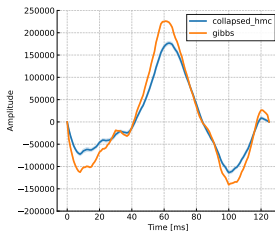


(a) 330x50ms.

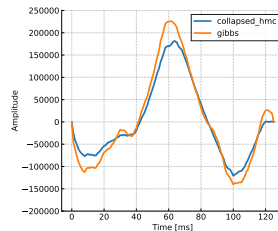
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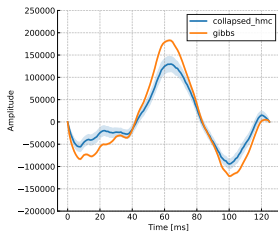
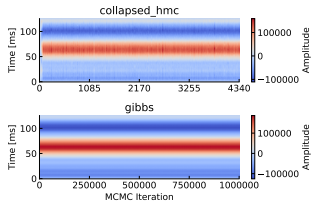


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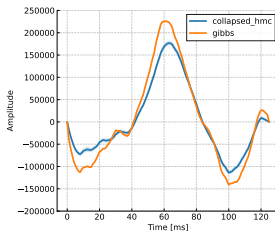
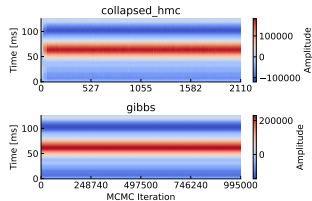


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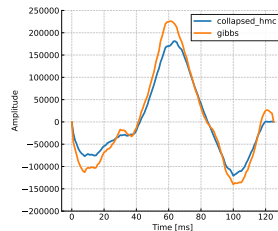
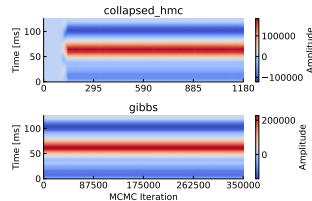
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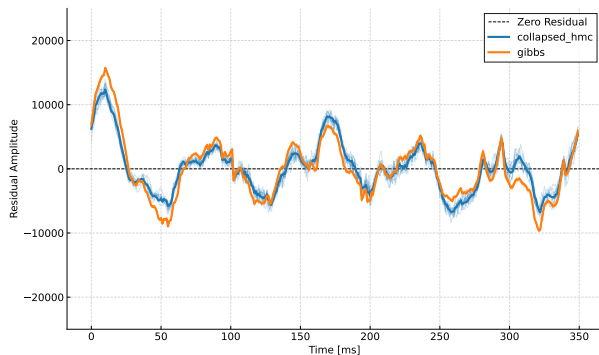


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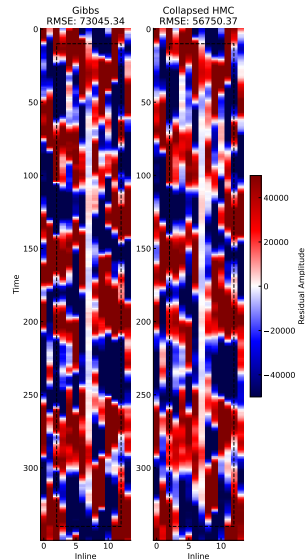


(a) 330x50ms.

# Model fit



(a) Well trace. RMSE: 4340 (G) vs 3611 (HMC).



(a) 330x10ms. RMSE: 73000 (G) vs 57000 (HMC).

# Conclusions

- Gibbs and HMC might be exploring different regions of the parameter space.
- Including data outside the well changes the wavelet estimation.

## References

- Buland, A. and Omre, H. (2003). Bayesian wavelet estimation from seismic and well data. *Geophysics*, 68, 2000–2009.
- Buland, A. and Omre, H. (2003). Joint AVO inversion, wavelet estimation and noise-level estimation using a spatially coupled hierarchical Bayesian model. *Geophysical Prospecting*, 51(6).
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